# Abstract Interpretation in Pisa



From 1987 -:

### The roots (and my roots)

- \* November 1987: I was looking for a subject....
- \* Giorgio gave me 2 papers:
  - \* Abstract Interpretation or Partial Evaluation?

### The alternative....

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ABSTRACT INTERPRETATION: A UNIFIED LATTICE MODEL FOR STATIC ANALYSIS
OF PROGRAMS BY CONSTRUCTION OR APPROXIMATION OF FIXPOINTS

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### 1. Introduction

### 2. Summary

Section 3 describes the syntax and mathematical semantics of a simple flowchart language, Scott and Strachey 711. This mathematical semantics is used in section 4 to built a more abstract model of the semantics of programs, in that it ignores the sequencing of control flow. This model is taken to be the most concrete of the abstract interpretations of programs. Section 5 gives the formal definition of the abstract interpretations of a program.

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Abstract program properties are modeled by a complete semilattice, Birkhoff[61]. Elementary program constructs are locally interpreted by order preserving functions which are used to associate a system of recursive equations with a program. The program global properties are then defined as or of the extreme fixpoints of that system, Tarski [55]. The abstraction process is defined in section 6. It is shown that the program properties obtained by an abstract interpretation of a program are consistent with those obtained by a more refined interpretation of that program. In particular, an abstract interpretation may be shown to be consistent with the formal semantics of the language. Levels of abstraction are formalized by showing that consistent abstract interpretations form a lattice (section 7). Section 8 gives a constructive definition of abstract properties of programs based on constructive definitions of fixpoints. It shows that various classical algorithms such as Kildall 73], Wegbreit[75] compute program properties as limits of finite Kleene [52]'s sequences. Section 9 introduces finite fixpoint approximation methods to be used when Kleene's sequences are infinite, Cousot[76]. They are shown to be consistent with the abstraction process. Practical examples illustrate the various sections. The conclusion points out that abstract interpretation of programs is a unified approach to apparently unrelated program analysis techniques.

### 3. Syntax and Semantics of Programs

We will use finite flowcharts as a language independent representation of progrems.

### 3.1 Syntax of a Program

A program is built from a set "Nodes". Each node has successor and predecessor nodes :  $\underline{n\text{-succ}}, \ \underline{n\text{-pred}} \ : \ \text{Nodes} + 2^{\underline{Nodes}} \mid \ (m \in \underline{n\text{-succ}}(n))$ 

Hereafter, we note |S| the cardinality of a set S. When |S|=1 so that  $S=\{x\}$  we sometimes use S to

The node subsets "Entries", "Assignments", "Tests", "Junctions" and "Exits" partition the set Nodes.

- An entry node (n  $\in$  Entries) has no predecessors and one successor, ((n-nred(n) =  $\emptyset$ ) and (|n-succ(n)| = 1)).

### PARTIAL EVALUATION AS A MEANS FOR INFERENCING DATA STRUCTURES IN AN APPLICATIVE LANGUAGE: A THEORY AND IMPLEMENTATION IN THE CASE OF PROLOG

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### ABSTRACT

An operational semantics of the Prolog programming language is introduced. Meta-IV is used to specify the semantics. One purpose of the work is to provide a specification of an implementation of a Prolog interpreter. Another one is an application of this specification to a formal description of program optimization techniques based on the principle of partial evaluation.

Transformations which account for pruning, forward data structure propagation and opening (which also provides backward data structure propagation) are formally introduced and proved to preserve meaning of programs. The so defined transformations provide means to inference data structures in an applicative language. The theoretical investigation is then shortly related to research in rule-based systems and logic.

An efficient well-integrated partial evaluation system is available in Qlog - a Lisp programming environment for Prolog.

### 1.0 INTRODUCTION

It is very likely that a large part of future programming will be programming in increasingly higher level languages. In such languages more attention will be paid to efficient problem solving, whereas this efficiency need not reflect the requirements of an efficient computation. In these circumstances program transformation tools will play the central role in making the efficiency realistic. It is also felt that the tools should be interactive. One reason is that they are to support the user in the immanently interactive activities of programming. The other one is that due to the complexity of some transformations the user's support might be indispensable in some points.

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The growing interest in applicative languages programming has also given much impulse to research concerned with Prolog (which is a good example of an applicative and rather high level programming language). At the same time the perceived inefficiency in execution of many applicative languages has been an obstacle to their wide-spread acceptance. Consequently, algorithms are often coded for efficient execution at the expense of clarity. This compromises the applicative style which is the prime advantage of such languages.

We argue, that high-level program transformations can relieve the programmer from concern for efficiency in many cases. Several authors have considered the optimizing transformations and their applications, while relatively little attention has been paid to the so called partial evaluation transformations. Unfortunately, even if partial evaluation seems to be a very powerful and useful tool it has not been given any precise definition.

In this paper we investigate partial evaluation of Prolog programs as a part of a theory of interactive, incremental programming. The goal of this investigation is to provide formally correct, interactive programming tools for program transformation. Moreover, partial evaluation as introduced in the paper is not only a means to improve program efficiency but also a means for inferencing data structures in an applicative language.

The rest of this paper is organized as follows. First, an informal introduction of partial evaluation and a short discussion of related research is presented. Second, after the preliminaries which establish the conventions and notation, an abstract Prolog machine is introduced. The machine is then extended to account for partial evaluation transformations. A partial evaluation system is implemented in the Qlog system according to the specification. Finally, a brief discussion of relations between logic, partial evaluation and research in rule-based systems follows.

### 2.0 PARTIAL EVALUATION: AN INTRODUCTION

An informal introduction to partial evaluation is presented here and illustrated with a simple example.

The goal of partial evaluation is to transform programs into more efficient ones. The improved efficiency is obtained at the expense of the generality of the programs. The restrictions on generality are usually introduced by setting

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### The choice....

7. DESIGN OF THE APPROXIMATE PREDICATE TRANSFORMER HEDREM 6.4.0.2 INDUCED BY A SPACE OF APPROXIMATE ASSERTIONS (1) - Let I be a principal ideal and J be a dual semiideal of a complete lattice  $L(E,I,T,U,\Pi)$ . If InJ is nonvoid then InJ is a complete and convex In addition to A and Y the specification of a sub-join-semilattice of L.

(2) - Every complete and convex sub-join-semilattice In addition to A and Y the Specification of the choice program analysis framework also includes the choice of an approximate predicate transformer tx([+ (A + A)] ()) or en approximate predicate transformer tell (14 (4 A))

(or e monoid of maps on A plus a rule for associating maps to program statements (e.g. Rosen(781)).

We now show that in fact this is not indispensable.

Since there exists a best correct choice of T which is induced by A and the formal semantics of the considered opportunity. C of L can be expressed in this form with  $I = \{x \in L : x \in (UC)\}$  and  $\{x \in L : \{\frac{1}{2}y \in C : y \in x\}\} \subseteq J$ . -> THEOREM 6.4.0.3 Let  $\{I_i \in \Delta\}$  be a family of principal ideals of the complete lattice  $L(E_i, I, T_i, L_i, \Lambda)$  containing L. Then  $\lambda \times U(n I_i : i \in \Delta \land \times c I_i)$  is an upper closure operator sidered programming language. 7.1 A Reasonable Definition of Correct Approximate \_ \on L. Predicate Transformers D Example 6.4.0.4 At paragraph 3, given  $(V, A, \tau)$  the minimal assertion which is invariant at point i of a program  $\pi$  with entry specification och was defined as : The following lattice can be used for static analysis of the signs of values of numerical variav ?(p)(¢)  $p_i = pepath(i)$ Therefore the minimal approximate invariant assertion is the least upper approximation of  $\mathsf{P}_1$  in  $\mathsf{A}$  that is :  $\rho(P_i) = \rho(v \tilde{\tau}(p)(\phi))$   $p \in path(i)$ Even when path(i) is a finite set of finite paths the Even when path(i) is a finite set of finite paths the evaluation of  $\tau(p)(\phi)$  is hardly machine-implementable since for each path  $p=a_1,\ldots,a_m$  the computation sequence  $X_0=\phi$ ,  $X_1=\tau(C(a_1))(X_0),\ldots,X_m=\tau(C(a_m))(X_m)$  does not necessarily only involve elements of  $\overline{A}$  and  $(\overline{A}+\overline{A})$ . Therefore using  $\overline{\phi}(\overline{A})$  and  $t\in (\mathbb{N}+\overline{A})$  a machine representable sequence  $\overline{X}_0=\phi$ ,  $\overline{X}_1=\tau(C(a_m))(\overline{X}_m)$ . ...  $\overline{X}_m=\tau(C(a_m))(\overline{X}_{m-1})$  is used instead of  $X_0,\ldots,X_m$  which leads to the expression : (where 1, -,  $\cdot$ , -,  $\times$ 0, 1,  $\top$  respectively stand for  $\lambda x.false$ ,  $\lambda x.x<0$ ,  $\lambda x.x>0$ ,  $\lambda x.x<0$ ,  $\lambda x.x=0$ ,  $\lambda x.x>0$ , \(\lambda.false, \lambda.x.\text{xv.}, \lamb  $Q_1 = \rho(v_{\overline{t}(p)(\overline{\phi})})$   $p \in path(1)$ The choice of  $\overline{t}$  and  $\overline{\varphi}$  is correct if and only if  $\mathbb{Q}_1$  is an upper approximation of  $\mathbb{P}_1$  in  $\overline{A}$  that is if and  $\tilde{\tau}(p)(\phi)) \Rightarrow \rho(v) \tilde{\tilde{\tau}}(p)(\bar{\phi}))$ p ∈ path(1) pepath(1) In particular for the entry point we must have  $\varphi \Longrightarrow \rho(\overline{\varphi}) = \overline{\varphi}$  so that we can state the following : an upper closure operator p : DEFINITION 7.1.0.1 (CORRESTERZA) (1) An approximate predicate transformer tε(L + (A + A)) is said to be a correct upper approximation of tε(L + (A + A)) in A=p(A) if and only if for all φeA, φeA such that φ=φ and only if for all φeA, φeA such that φ=φ and program T we have :  $MOP_{\pi}(\tau, \phi) \Rightarrow MOP_{\pi}(t, \phi)$  (2) Similarly if  $A \triangleright (\alpha, \gamma) A$ ,  $t \in (L + (A + A))$  is said to be a correct upper approximation of  $\tau \in (L^+(A-A)) \text{ in } A=\alpha(A) \text{ if and only if } \forall \phi, \forall \phi: \phi \Rightarrow \gamma(\delta), \forall \pi, \alpha(\mathsf{MOP}_\pi(\tau,\phi)) \subseteq \mathsf{MOP}_\pi(t,\phi)),$  (i.e.  $\mathsf{MOP}_\pi(\tau,\phi) \Rightarrow \gamma(\mathsf{MOP}_\pi(t,\phi))$ This global correctness condition for  $\overline{t}$  is very difficult to check since for any program  $\pi$  and any program point i all paths proparal full must be considered. However it is possible to use instead the following equivalent local condition which can be checked for every type of statements : and the space of approximate assertions (used in ex-End of Example. 276

is modified while a new one is pushed on the stack (.15). The explanation is that it must contain the "history" of selecting a clause from the program. (And at the same time such a solution was preferred to the use of a side-effect which could be introduced by the is-uni procedure.) Should a backtrack occur (ie popping an element from the stack) then a new trial must be made in that very program. An alternative approach which carries the history forward and stores it in the top configuration requires popping two configurations while backtracking. The reader is encouraged to write such a version of apm.

The apm function can be simply made recursive as well. Informally speaking, it is sufficient to encapsulate right sides of the conditionals (except undefined (.6)) in a call to apm (and change its type definition) and add a check if the stack is not empty.

### 4.6 Semantics

### Computation Sequence

Given the definition of apm, a computation (sequence) of a literal A determined by a program P is defined recursively as follows:

Before we proceed to the definition of the semantics, an additional function sema is introduced.

### Definition 2

$$\mathsf{Sem}^{\alpha} : \mathsf{Pro} \to \mathsf{Lit} \to \mathsf{State}^{\infty}$$

where  $\operatorname{sem}^{\alpha}$ . P. A is the longest computation of A determined by P.

### Definition 3

The semantics sem of A determined by P is defined in the following way:

 $2^{\circ}$  Let A and P be given and established. From sem<sup> $\alpha$ </sup>, P. A a subsequence is selected which contains all the elements such that: stt; = mk-State(mk-Conf(Pi, Bi, Oi)^stki, diri),

where  $B_i = []$ , dir = forward.

sem. P. A 
$$\stackrel{\Delta}{=}$$
  $\{\theta_{il}, \theta_{i2}, ...\}$ 

Such a subsequence is called a successful computation sequence (for A determined by P) and abbreviated s.c.s.

### 5.0 PARTIAL EVALUATION

Informally speaking, a partial evaluation machine is an extended abstract Prolog machine which, while computing, labels those clauses (parts of a program) which contributed to a successful computation. Those labelled clauses form a subsequence P' of P such that the denotation of A in P is preserved in the new program P'. P is called a pruned version of P (with respect to A) and will be subject to further transformations.

in partial evaluation one also has to take a different approach to the so called under-defined programs. The partial evaluation machine should be total. However, instead of popping the stack and switching to the backward state in the case of undefined procedures (ie. backtracking, as it was the case in the regular interpreter) we rather assume that a definition will be provided later, and thus the forward state is preserved. These concepts are formalized in the following way.

The essential change is in the definition of configuration. It is now defined as follows:

The change induces the following natural modification in the definition of is-uni. (The is-def function's text remain unchanged, although the function is defined on a new domain).

```
8. is-uni. A. P ≜
    P = €
                                 → failmatch.
         let mk-Cla(H, B) = first. P in
          name. H = name. A →
                 (let \Delta = uni (H, A) in
                     mk-Conf(tail. P, B, A, mk-Cla(H, B)),
                     is-uni. A. (tail. P) ),
             is-uni. A. (tail. P)
```

The more significant change is in the definition of apm. In the case of partial evaluation this function is total.

9. apm. P. mk-State(stk, dir) ≜ let mk-Conf(P<sub>1</sub>, B<sub>1</sub>,  $\Theta_1$ , C<sub>1</sub>) = first, stk in cases dir: forward → (B<sub>1</sub> = □ → mk-State(tail. stk, backward), cases is-def. (first. B<sub>1</sub>). P: break mk-State(mk-Conf(P, tail.  $B_1$ ,  $\theta$ ,  $\epsilon$ )^ mk-Conf( $\mathcal{E}$ ,  $\mathcal{B}_l$ ,  $\Theta_l$ ,  $\mathcal{C}_l$ ) tail. stk, forward) .6b failmatch .7 mk-State(tail. stk, backward) mk-Conf(P', B', A, C') mk-State(mk-Conf(P, Δ. (B'^tail. B<sub>I</sub>), Δ. Θ<sub>I</sub>, C')^ .9 mk-Conf(P1, B1, B1, C1)^tail. stk, forward)) .10 .11 .12 cases is-def. (first. B<sub>1</sub>). P<sub>1</sub>: mk-Conf(P', B', A, C') .13 mk-state(mk-Conf(P, Δ. (B'^tail. B<sub>I</sub>), Δ. Θ<sub>I</sub>, C')^ .14 mk-Coni(P1, B1, θ1, C1)^tail. stk, forward) .15 T → mk-State(tall.stk, backward)

### Annotations

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We annotate below only the significantly modified part of the apm's definition.

.6 break, then a new state is created such that the elements of the top configurations are: the global program P, the tail of previous body, the previous

# The beginning.....

- Giorgio was of course already interested in semantics and correctness of symbolic interpreters!!!
  - Giorgio Levi, Franco Sirovich:
     Proving Program Properties, Symbolic
     Evaluation and Logical Procedural
     Semantics. MFCS 1975: 294-301

### PROVING PROGRAM PROPERTIES, SYMBOLIC EVALUATION AND LOGICAL PROCEDURAL SEMANTICS

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### Introduction

The semantics of programming languages has received a good deal of consideration because it is an essential part of the definition of a programming language and provides a sound basis for interpreter design. The interest in this field has been emphasized because of its relationship to proving properties of programs. Some recent results (Boyer and Moore [1,2], Burstall [3] and Topor [4]) have shown that interpreters can be extended to cope with the task of proving properties of programs. This task requires the (symbolic) interpreter to be able to deal with symbolic values (i.e. expressions containing quantified variable symbols) and to make use of induction rules.

We are concerned with the problem of defining general methods for generating symbolic interpreters for programming languages. Any such method must depend on a description of the programming language semantics providing a characterization of the language in terms of a suitable symbolic logic. In the paper we will introduce a calculus (Term Equation Language) and its symbolic interpreter. TEL has a straightforward logical interpretation. Programming language semantics is given by means of a set of TEL axioms which provide through the TEL interpreter a symbolic interpreter for the programming language.

### ...and Barbuti?

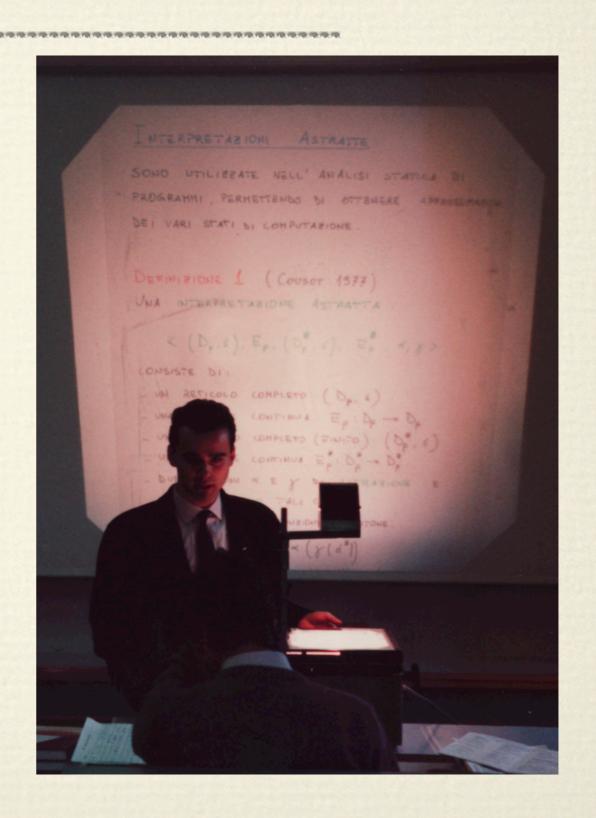
- A great paper: Roberto Barbuti,
  Alberto Martelli: A Structured
  Approach to Static Semantics
  Correctness. Sci. Comput. Program.
  3(3): 279-311 (1983).
  - This is where I have understood correctness of static semantics!
  - \* ....simple and clean!





# The beginning...

- ❖ In Pisa: Roberto Barbuti, Roberto Giacobazzi, Giorgio Levi: A General Framework for Semantics-Based Bottom-Up Abstract Interpretation of Logic Programs. ITCS 1989 and later in ACM TOPLAS.
- \* In Padova: Christian Codognet, Philippe Codognet, Gilberto Filé: Yet Another Intelligent Backtracking Method. ICLP/ SLP 1988: 447-465.
- The big (theological) deal: **bottom-up** or **top-down?**



# The great days!!

- \* In Pisa in the 90s:
  - The best group in semantics of Logic Programming!
  - Strong mathematical bases!
  - Challenging projects!
  - International environment
  - \* Enthusiasm!



### The Cousots exist!

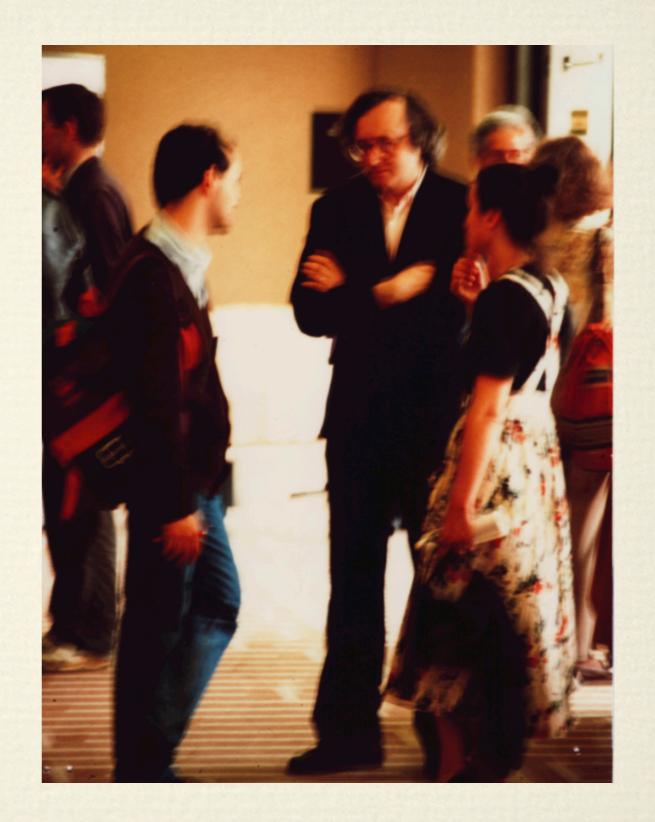
ICLP'91: a joint workshop on

Abstract Interpretation in Logic

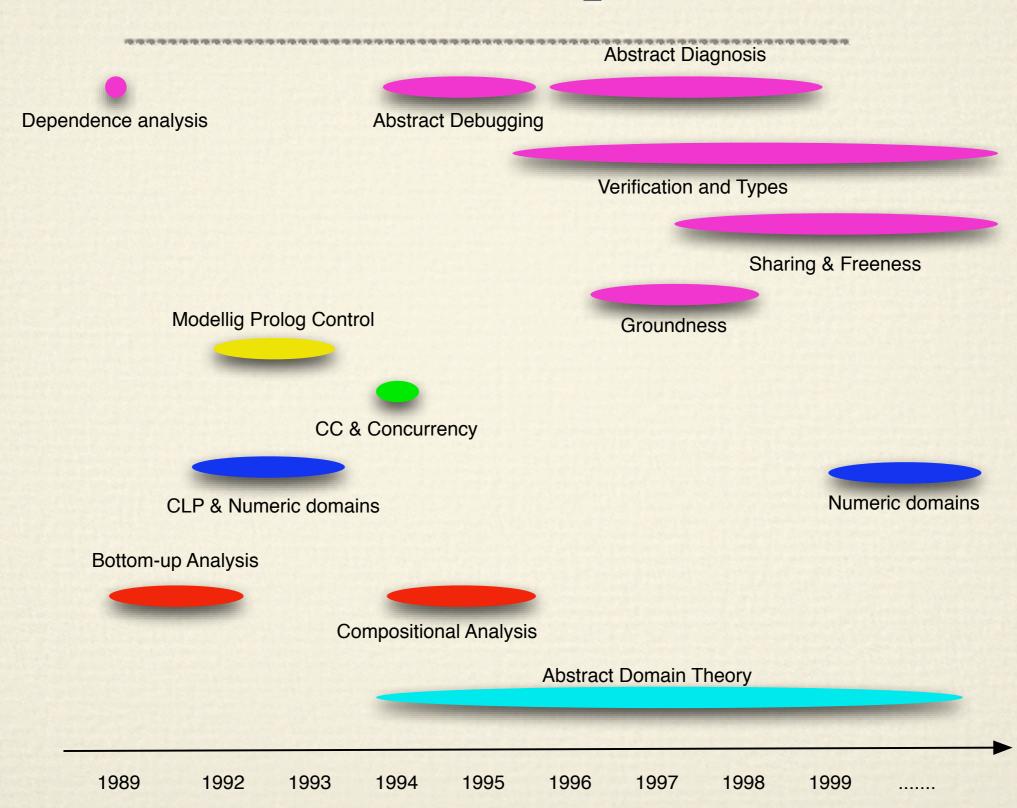
Programming

... in Paris!

and then: WSA, SAS, etc..



### The Abstract Interpretation slice



### Abstract Interpretation and People

Giorgio Levi Roberto Barbuti Roberto Giacobazzi

Michael Maher

**Roberto Bagnara** Saumya Debray

Enea Zaffanella

Francesco Ranzato

Francesca Scozzari

Agostino Cortesi

Catuscia Palamidessi Moreno Falaschi

> Gilberto Filè Giuliana Vitiello

Maria Chiara Meo Marco Comini Paolo Volpe Roberta Gori Fausto Spoto Gianluca Amato Francesca Levi

> Patricia M. Hill Francois Fages

Sergio Maffeis



### Spreading ideas and people



# The chance of being in Pisa